

Regulators and computations of Mahler measures

Mahler Measure in Mobile, University of South Alabama, Mobile, AL

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Mahler measure

Definition 1 For $P \in \mathbb{C}[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$, the (logarithmic) Mahler measure is defined by

$$m(P) = \frac{1}{(2\pi i)^n} \int_{\mathbb{T}^n} \log |P(x_1, \dots, x_n)| \frac{dx_1}{x_1} \dots \frac{dx_n}{x_n}. \quad (1)$$

The simplest example in several variables is due to Smyth [11]

$$m(1 + x + y) = \frac{3\sqrt{3}}{4\pi} L(\chi_{-3}, 2) = L'(\chi_{-3}, -1)$$

$$L(\chi_{-3}, s) = \sum_{n=1}^{\infty} \frac{\chi_{-3}(n)}{n^s} \quad \chi_{-3}(n) = \begin{cases} 1 & n \equiv 1 \pmod{3} \\ -1 & n \equiv -1 \pmod{3} \\ 0 & n \equiv 0 \pmod{3} \end{cases}$$

Polylogarithms

Many examples should be understood in the context of polylogarithms.

Definition 2 The k th polylogarithm is the function defined by the power series

$$\text{Li}_k(x) := \sum_{n=1}^{\infty} \frac{x^n}{n^k} \quad x \in \mathbb{C}, \quad |x| < 1. \quad (2)$$

This function can be continued analytically to $\mathbb{C} \setminus [1, \infty)$.

In order to avoid discontinuities, and to extend polylogarithms to the whole complex plane, several modifications have been proposed. Zagier [12] considers the following version:

$$\widehat{\mathcal{L}}_k(x) := \widehat{\text{Re}}_k \left(\sum_{j=0}^{k-1} \frac{2^j B_j}{j!} (\log |x|)^j \text{Li}_{k-j}(x) \right), \quad (3)$$

where B_j is the j th Bernoulli number, and $\widehat{\text{Re}}_k$ denotes Re or iIm depending on whether k is odd or even.

This function is one-valued, real analytic in $\mathbb{P}^1(\mathbb{C}) \setminus \{0, 1, \infty\}$ and continuous in $\mathbb{P}^1(\mathbb{C})$. Moreover, $\widehat{\mathcal{L}}_k$ satisfy very clean functional equations. The simplest ones are

$$\widehat{\mathcal{L}}_k \left(\frac{1}{x} \right) = (-1)^{k-1} \widehat{\mathcal{L}}_k(x) \quad \widehat{\mathcal{L}}_k(\bar{x}) = (-1)^{k-1} \widehat{\mathcal{L}}_k(x).$$

There are also lots of functional equations which depend on the index k . For instance, for $k = 2$, we have the Bloch–Wigner dilogarithm,

$$D(x) := \operatorname{Im}(\operatorname{Li}_2(x)) + \arg(1-x) \log|x|$$

which satisfies the well-known five-term relation

$$D(x) + D(1-xy) + D(y) + D\left(\frac{1-y}{1-xy}\right) + D\left(\frac{1-x}{1-xy}\right) = 0. \quad (4)$$

The relation with regulators

We write the Mahler measure as an integral of a certain $\mathbb{R}(n-1)$ -valued smooth $n-1$ -form in $X(\mathbb{C})$, the variety determined by the zeroes of the polynomial.

$$m(P) = m(P^*) + \frac{1}{(-2\pi i)^{n-1}} \int_{\Gamma} \eta_n(n)(x_1, \dots, x_n)$$

where

$$\Gamma = \{P(x_1, \dots, x_n) = 0\} \cap \{|x_1| = \dots = |x_{n-1}| = 1, |x_n| \geq 1\}$$

This was an idea of Deninger [3].

As an example, let us look at Smyth's case in two variables ([11]). The two-variable differential form is

$$\eta_2(2)(x, y) = \log|x| \operatorname{di} \arg y - \log|y| \operatorname{di} \arg x.$$

Then

$$m(1+x+y) = \frac{1}{(2\pi i)^2} \int_{\mathbb{T}^2} \log|1+x+y| \frac{dx dy}{x y}.$$

By Jensen's equality:

$$\begin{aligned} &= \frac{1}{2\pi i} \int_{\mathbb{T}^1} \log^+ |1+x| \frac{dx}{x} \\ &= \frac{1}{2\pi i} \int_{\Gamma} \log|y| \frac{dx}{x} = -\frac{1}{2\pi i} \int_{\Gamma} \eta_2(2)(x, y), \end{aligned}$$

where

$$\Gamma = \{1+x+y=0\} \cap \{|x|=1, |y| \geq 1\}.$$

Here are some properties of $\eta_n(n)(x_1, \dots, x_n)$:

- $\eta_n(n)$ is multiplicative in each variable and anti-symmetric. Hence it can be thought as a function on $\bigwedge^n (\mathbb{C}(X)^*)_{\mathbb{Q}}$.
- $d\eta_n(n)(x_1, \dots, x_n) = \widehat{\operatorname{Re}}_n \left(\frac{dx_1}{x_1} \wedge \dots \wedge \frac{dx_n}{x_n} \right)$
- There is an $\mathbb{R}(n-2)$ -valued smooth $n-2$ -form in $X(\mathbb{C})$ such that

$$\eta_n(n)(x, 1-x, x_1, \dots, x_{n-2}) = d\eta_{n-1}(n)(x, x_1, \dots, x_{n-2})$$

In the two-variable case we have

$$\eta_2(2)(x, 1-x) = d\widehat{D}(x).$$

The forms for $n = 3$ are

$$\begin{aligned} \eta_3(3)(x, y, z) &= \log|x| \left(\frac{1}{3} d \log|y| \wedge d \log|z| + d \arg y \wedge d \arg z \right) \\ &+ \log|y| \left(\frac{1}{3} d \log|z| \wedge d \log|x| + d \arg z \wedge d \arg x \right) + \log|z| \left(\frac{1}{3} d \log|x| \wedge d \log|y| + d \arg x \wedge d \arg y \right), \end{aligned}$$

$$\eta_3(3)(x, 1-x, y) = d\eta_3(2)(x, y),$$

$$\eta_3(2)(x, y) = \widehat{D}(x) d \arg y + \frac{1}{3} \log|y| (\log|1-x| d \log|x| - \log|x| d \log|1-x|).$$

Now the first variable of $\eta_n(n-1)$ behaves like the five-term relation.

As before, there is a $\mathbb{R}(n-3)$ -valued smooth $n-3$ -form in $X(\mathbb{C})$ such that

$$\eta_n(n-1)(x, x, x_1, \dots, x_{n-3}) = d\eta_n(n-2)(x, x_1, \dots, x_{n-3}).$$

The first variable in $\eta_n(n-2)$ behaves like the functional equations of the trilogarithm.

And so on...

Finally, the second to last form satisfies

$$\eta_n(2)(x, x) = d\eta_n(1)(x),$$

with

$$\eta_n(1)(x) = \widehat{\mathcal{L}}_n(x).$$

Let us take a look at Smyth's case for three variables. We can express the polynomial as $P(x, y, z) = (1-x) + (1-y)z$. We get:

$$m(P) = m(1-y) + \frac{1}{(2\pi i)^2} \int_{\mathbb{T}^2} \log^+ \left| \frac{1-x}{1-y} \right| \frac{dx dy}{x y} = -\frac{1}{(2\pi)^2} \int_{\Gamma} \eta_3(3)(x, y, z).$$

$$x \wedge y \wedge z = -x \wedge (1-x) \wedge y - y \wedge (1-y) \wedge x,$$

in other words,

$$\eta_3(3)(x, y, z) = -\eta_3(3)(x, 1-x, y) - \eta_3(3)(y, 1-y, x).$$

We have

$$m((1-x) + (1-y)z) = \frac{1}{4\pi^2} \int_{\gamma} \eta_3(2)(x, y) + \eta_3(2)(y, x).$$

On the other hand,

$$\eta_3(2)(x, x) = d\widehat{\mathcal{L}}_3(x).$$

We would like to apply Stokes' Theorem again. Observe that $\partial\Gamma = \{P(x, y, z) = 0\} \cap \{|x| = |y| = |z| = 1\}$. When $P \in \mathbb{R}[x, y, z]$, Γ can be thought as

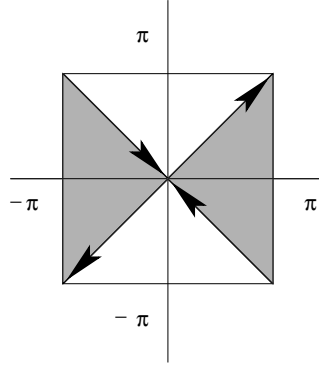
$$\gamma = \{P(x, y, z) = P(x^{-1}, y^{-1}, z^{-1}) = 0\} \cap \{|x| = |y| = 1\}.$$

Note that we are integrating now on a path inside the curve $C = \{P(x, y, z) = P(x^{-1}, y^{-1}, z^{-1}) = 0\}$. The differential form ω is defined in this new curve (this way of thinking the integral over a new curve has been proposed by Maillot). Now it makes sense to try to apply Stokes' Theorem.

Back to Smyth's case, in order to compute C we set $\frac{(1-x)(1-x^{-1})}{(1-y)(1-y^{-1})} = 1$ and we get $C = \{x = y\} \cup \{xy = 1\}$ in this example, and

$$-\{x\}_2 \otimes y - \{y\}_2 \otimes x = \pm 2\{x\}_2 \otimes x.$$

We integrate in the set described by the following picture



Then

$$m((1-x) + (1-y)z) = \frac{1}{4\pi^2} 8(\mathcal{L}_3(1) - \mathcal{L}_3(-1)) = \frac{7}{2\pi^2} \zeta(3).$$

New examples

Using this method we have been able to prove the following examples which were originally computed numerically by Boyd

$$m(x^2 + 1 + (x+1)y + (x-1)z) = \frac{L(\chi_{-4}, 2)}{\pi} + \frac{21}{8\pi^2} \zeta(3),$$

$$m(x^2 + x + 1 + (x+1)y + z) = \frac{\sqrt{3}}{4\pi} L(\chi_{-3}, 2) + \frac{19}{6\pi^2} \zeta(3).$$

An example in four variables

In [8] we computed this example

$$\pi^3 m \left(1 + x + \left(\frac{1-x_1}{1+x_1} \right) (1+y)z \right) = 2\pi^2 L(\chi_{-4}, 2) + 8 \sum_{0 \leq j < k} \frac{(-1)^{j+k+1}}{(2j+1)^3 k}.$$

With this method we have been able to prove that

$$= 24L(\chi_{-4}, 4).$$

In particular this implies

$$\sum_{0 \leq j < k} \frac{(-1)^{j+k+1}}{(2j+1)3^k} = 3L(\chi_{-4}, 4) - \frac{\pi^2}{4}L(\chi_{-4}, 2)$$

More generally, by using the Hurwitz zeta function we have been able to prove

$$\sum_{0 \leq j < k} \frac{(-1)^{j+k+1}}{(2j+1)^m k} = mL(\chi_{-4}, m+1) + \sum_{h=1}^{\frac{m-1}{2}} \frac{(-1)^h \pi^{2h} (2^{2h} - 1)}{(2h)!} B_{2h} L(\chi_{-4}, m-2h+1),$$

for m odd.

Generalized Mahler measure

Introduced by Gon & Oyanagi [4]

For $f_1, \dots, f_r \in \mathbb{C}[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$,

$$m(f_1, \dots, f_r) = \frac{1}{(2\pi i)^n} \int_{\mathbb{T}^n} \max\{\log |f_1|, \dots, \log |f_r|\} \frac{dx_1}{x_1} \dots \frac{dx_n}{x_n}$$

Note that in particular,

$$m(f_1, f_2) = m(f_1 + z f_2).$$

Examples

There is a particular case. Fix $P \in \mathbb{C}[x]$ and set $f_j = P(x_j)$.

Gon & Oyanagi [4] computed the following example

$$\begin{aligned} m(1-x_1, \dots, 1-x_{2m}) &= \frac{(-1)^{m+1} (2m)!}{\pi^{2m}} \zeta(2m+1) \\ &+ (2m)! \sum_{j=1}^m (-1)^j \frac{(1-2^{2j})}{(2m-2j)! (2\pi)^{2j}} \zeta(2j+1), \\ m(1-x_1, \dots, 1-x_{2m-1}) &= (2m-1)! \sum_{j=1}^{m-1} (-1)^j \frac{(1-2^{2j})}{(2m-2j-1)! (2\pi)^{2j}} \zeta(2j+1). \end{aligned}$$

Some particular cases are:

$$m(1-x_1, 1-x_2) = m(1-x_1 + z(1-x_2)) = \frac{7}{2\pi^2} \zeta(3),$$

$$m(1-x_1, 1-x_2, 1-x_3) = \frac{9}{2\pi^2} \zeta(3),$$

$$m(1-x_1, 1-x_2, 1-x_3, 1-x_4) = -\frac{93}{2\pi^4} \zeta(5) + \frac{9}{\pi^2} \zeta(3).$$

This example can be also computed using regulators. Using that $|P(x)|$ is monotonous when $0 \leq \arg x \leq \pi$ (in this case, $|P(x)| = 2 \left| \sin \frac{\arg x}{2} \right|$)

$$m(P(x_1), \dots, P(x_n)) = \frac{n!}{(\pi i)^n} \int_{0 \leq \arg x_n \leq \dots \leq \arg x_1 \leq \pi} \eta(P(x_1), x_1, \dots, x_n)$$

We have been able to also compute this example

$$\begin{aligned}
m \left(\frac{1-x_1}{1+x_1}, \dots, \frac{1-x_{2m}}{1+x_{2m}} \right) &= \frac{(-1)^{m+1} (2m)! (2^{2m+1} - 1)}{(2\pi)^{2m}} \zeta(2m+1) \\
&\quad + (2m)! \sum_{j=1}^m (-1)^j \frac{(1-2^{2j+1})}{(2m-2j)! (2\pi)^{2j}} \zeta(2j+1), \\
m \left(\frac{1-x_1}{1+x_1}, \dots, \frac{1-x_{2m-1}}{1+x_{2m-1}} \right) &= (2m-1)! \sum_{j=1}^{m-1} (-1)^j \frac{(1-2^{2j+1})}{(2m-2j-1)! (2\pi)^{2j}} \zeta(2j+1).
\end{aligned}$$

Some particular cases:

$$m \left(\frac{1-x_1}{1+x_1}, \frac{1-x_2}{1+x_2} \right) = m \left(\frac{1-x_1}{1+x_1} + z \left(\frac{1-x_2}{1+x_2} \right) \right) = \frac{7}{\pi^2} \zeta(3),$$

$$m \left(\frac{1-x_1}{1+x_1}, \dots, \frac{1-x_3}{1+x_3} \right) = \frac{21}{2\pi^2} \zeta(3),$$

$$m \left(\frac{1-x_1}{1+x_1}, \dots, \frac{1-x_4}{1+x_4} \right) = -\frac{93}{\pi^4} \zeta(5) + \frac{21}{\pi^2} \zeta(3).$$

Finally, we computed the following

$$m(1+x_1-x_1^{-1}, \dots, 1+x_n-x_n^{-1}) = \text{combination of polylogarithms.}$$

Some particular cases include

$$m(1+x_1-x_1^{-1}) = -\log(\varphi),$$

$$m(1+x_1-x_1^{-1}, 1+x_2-x_2^{-1}) = \frac{1}{\pi^2} \operatorname{Re}(\operatorname{Li}_3(\varphi^2) - \operatorname{Li}_3(-\varphi^2) + \operatorname{Li}_3(\varphi^{-2}) - \operatorname{Li}_3(-\varphi^{-2}))$$

for $\varphi = \frac{-1+\sqrt{5}}{2}$.

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